

Efficient Representation of Numerical Optimization Problems for SNARKs

Sebastian Angel, Andrew Blumberg, Eleftherios Ioannidis, Jess Woods

Example: School Admissions



1. School **commits** to secret admissions criteria
2. Students apply to school

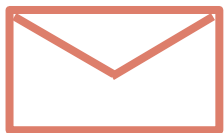


3. School **commits** to students' materials



4. School can then **prove (in zero knowledge)** that they admitted the best (most optimal) applicants given its criteria, without leaking criteria or information about specific students

Example: School Admissions



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GPA > 3.0, SAT > 500, sports + music > 1, incoming class enrollment < 200
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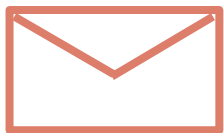


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Example: School Admissions



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GPA > 3.0, SAT > 500, sports + music > 1, incoming class enrollment < 200
2. Students apply to school



3. School **commits** to students' materials
Jane Doe, GPA 3.5, SAT 720, sports; Joe Public, GPA 2.9, SAT 530, music; ...
4. School can then **prove (in zero knowledge)** that they admitted the best (most optimal) applicants given its criteria, without leaking criteria or information about specific students



Optimization Problems

- Resource allocation
- Stocks and marketing
- Transportation
- Scheduling



Linear programming

- Circuit manufacturing
- Matrix completion
- Neural network training



Semidefinite
programming



Stochastic gradient
descent

Naive Solution

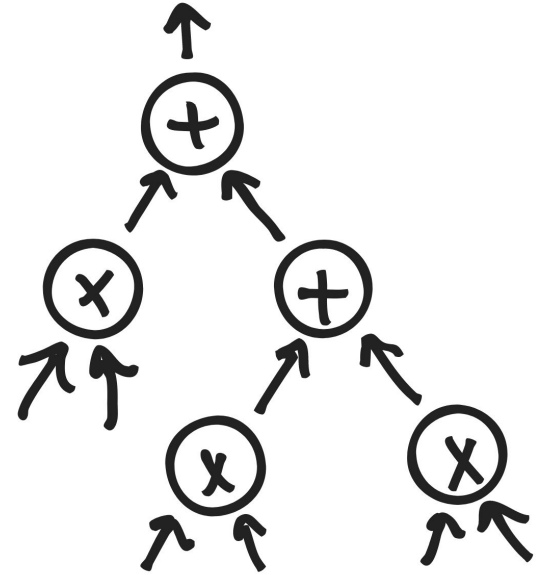
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void simplex(Tableau tableau) {
    add_slack_variables(tableau);

    while( true ) {
        int pivot_col = find_pivot_column(tableau);
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            optimal_vector(tableau);
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        int pivot_row = find_pivot_row(tableau, pivot_col);
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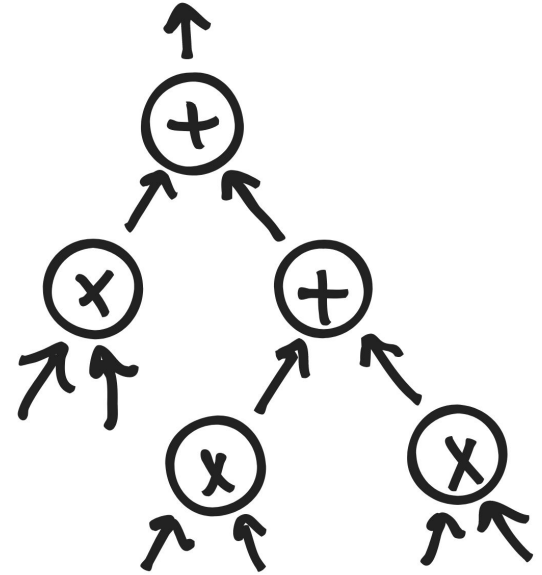
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Otti

Don't reason about solver implementation.

Leverage nondeterminism to reason about the solution.

Automated & Practical!



The rest of the talk

- We'll follow Otti through a **linear programming** problem
 - (See the paper for methods on **semidefinite programming** and **stochastic gradient descent**)
- Examine how to use Otti
- Limitations and Conclusion



Linear Programming Problems

Find a vector \mathbf{x} that maximizes $\mathbf{c}^T \cdot \mathbf{x}$

Subject to: $\mathbf{Ax} \leq \mathbf{b}$

$\mathbf{x} \geq \mathbf{0}$

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Find a vector \mathbf{y} that minimizes $\mathbf{b}^T \cdot \mathbf{y}$

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Certificate of Optimality for Linear Programming

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Given solutions \mathbf{x}^* , \mathbf{y}^* ...

Primal feasibility: $\mathbf{Ax}^* \leq \mathbf{b}$
 $\mathbf{x}^* \geq \mathbf{0}$

Dual feasibility: $\mathbf{A}^T \mathbf{y}^* \geq \mathbf{c}$
 $\mathbf{y}^* \geq \mathbf{0}$

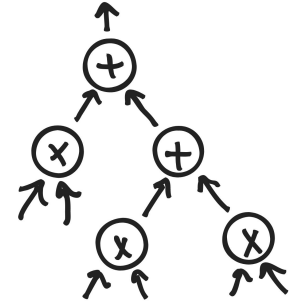
Strong Duality: $\mathbf{c}^T \cdot \mathbf{x}^* = \mathbf{b}^T \cdot \mathbf{y}^*$

Certificate of Optimality for Linear Programming

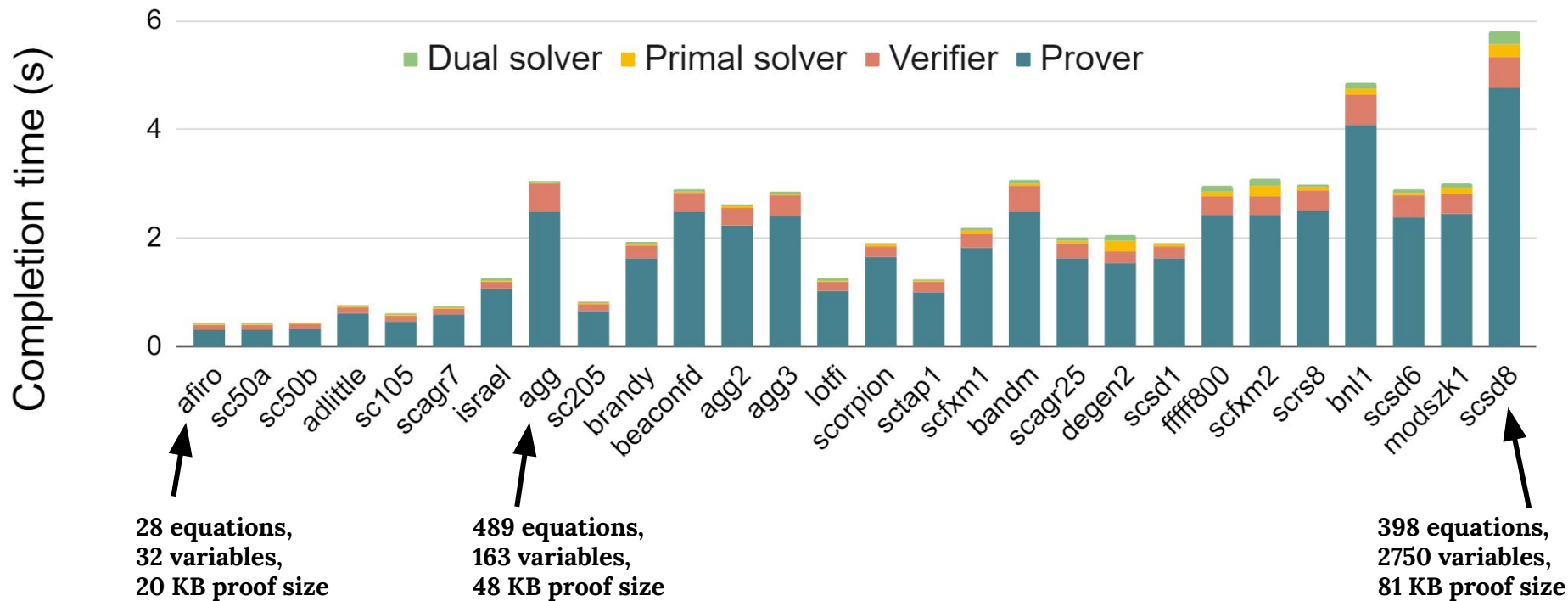
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How well does Otti work for Linear Programming?



Flow of Otti

Find a vector \mathbf{x} that maximizes
objective function

Subject to **constraints**



Prover

$\mathbf{x}^*, \mathbf{y}^* =$

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Solver

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Solver

$\pi =$

Primal feasibility
Dual feasibility
Strong Duality

Flow of Otti

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Solver

$\pi =$

Primal feasibility
Dual feasibility
Strong Duality

Verifier

π validates \mathbf{x}^* ?

ACCEPT or
REJECT

$\pi,$
 $\mathbf{x}^*, \mathbf{y}^*$

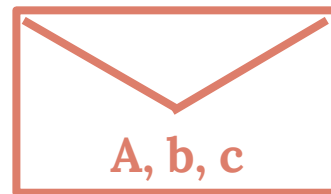


What the Verifier sees

Primal feasibility: $Ax^* \leq b$
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Strong Duality: $c^T \cdot x^* = b^T \cdot y^*$



solution x^*, y^*

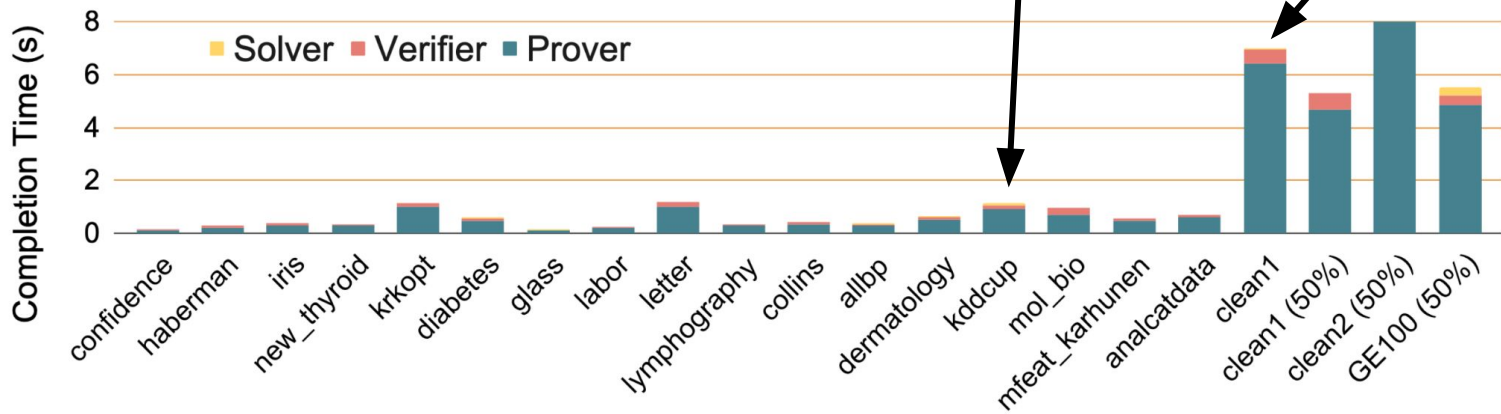
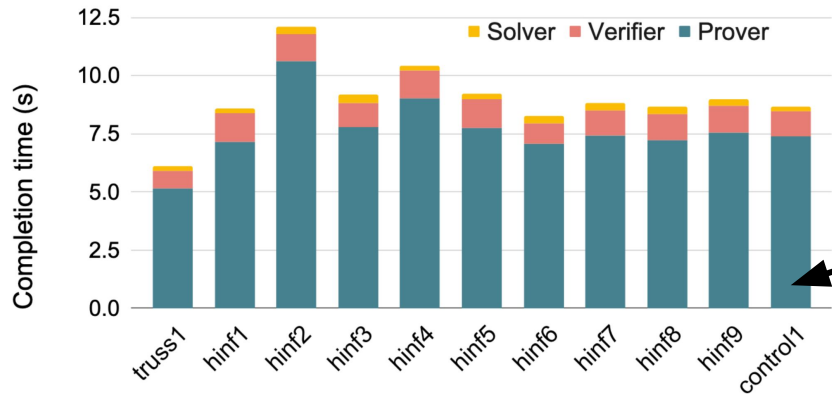


$_ \cdot x^* \leq _$
 $x^* \geq 0$

$_ ^T \cdot y^* \geq _$
 $y^* \geq 0$

$_ ^T \cdot x^* = _ ^T \cdot y^*$

How well does Otte work for SDP and SGD?



Limitations

- Still an upper size limit
- Compilation is still a bottleneck
- Problems must have specific structure
- Overhead (where the baseline is unverifiable solvers)

Takeaways

Otti . . .

- Demonstrates the effectiveness of **nondeterministic checkers**
- **Automates** entire pipeline
- Proves optimality on **real world datasets**
- **Over 4 orders of magnitude faster** than any existing approach

<https://github.com/eniac/otti>